

Advanced Machine Learning for Event Classification on PMU Data

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Joint work with:

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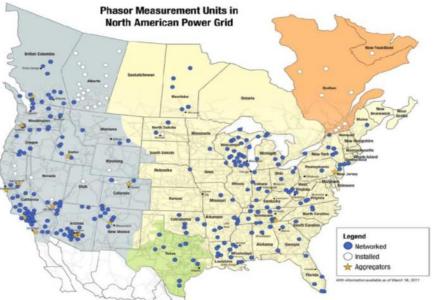
Objective: A pro-active approach to improving the *reliability* and *situational awareness* of power systems based on **detection** and **classification of** <u>*local*</u> and <u>*global*</u> events

Data: Sparsely located PMU devices deployed across three US interconnections:

- Eastern Interconnection
- Western Interconnection
- Texas (ERCOT) Interconnection

Existing solutions: Traditional ML models

- challenges: *high dimensionality, autocorrelation,* etc.
- require adaptations in model design and evaluation
- rely on *missing, unreliable,* or *imprecise* labels
- do not characterize local vs global events
- typically utilize only a single PMU variable



<u>Our approach:</u>

- Utilize all available channels, as well as each channel separately
- Consider representationally more advanced methods (capable of modeling signal data)
- Employ automated feature learning
- Analyze the effect of different labelling mechanisms on *local/global* event characterization

Pavlovski, M., Alqudah, M., Dokic, T., Hai, A. A., Kezunovic, M., Obradovic, Z. "Use of Hierarchical Convolutional Neural Networks for Event Classification on PMU Data", in review. This work is a part of **"Big Data Synchrophasor Monitoring and Analytics for Resiliency Tracking (BDSMART)" project** funded by the **US Department of Energy (DOE)**.



Prediction Methods

Model Variants

Traditional

- Decision Tree (DT)
- Logistic Regression (LR)
- Multilayer Perceptron (MLP)
- Support vector machine (SVM)

Single-channel CNN

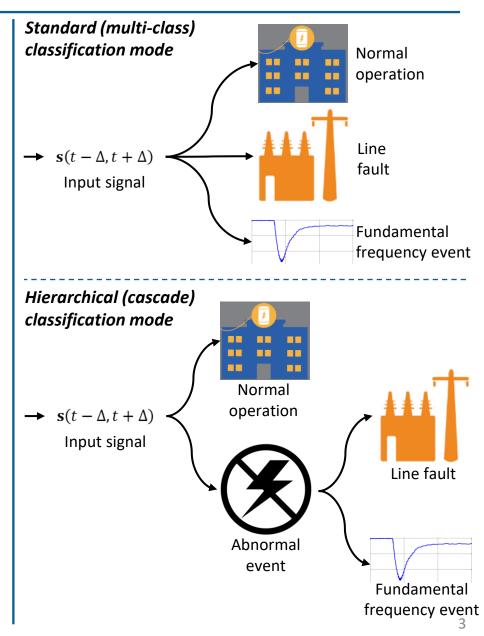
• Single-channel Convolutional Neural Network (SC-CNN)

Multi-channel CNN

- Parallel Channel Filtering CNN (PCF-CNN)
- Simultaneous Channel Filtering CNN (SCF-CNN)

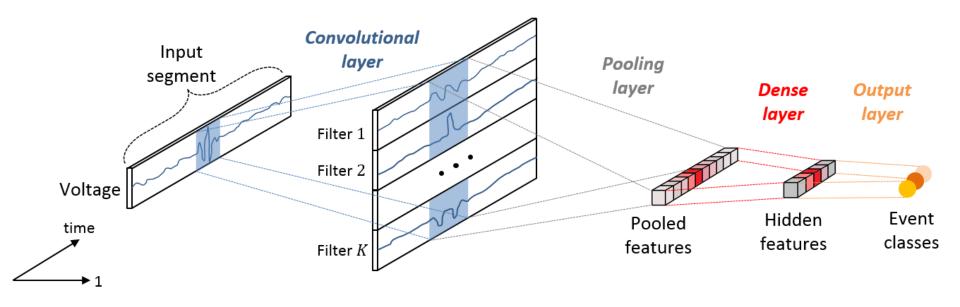
Classification modes

- o Standard (multi-class)
- o Hierarchical (cascade)
 - Detected events are classified into line or freq. events



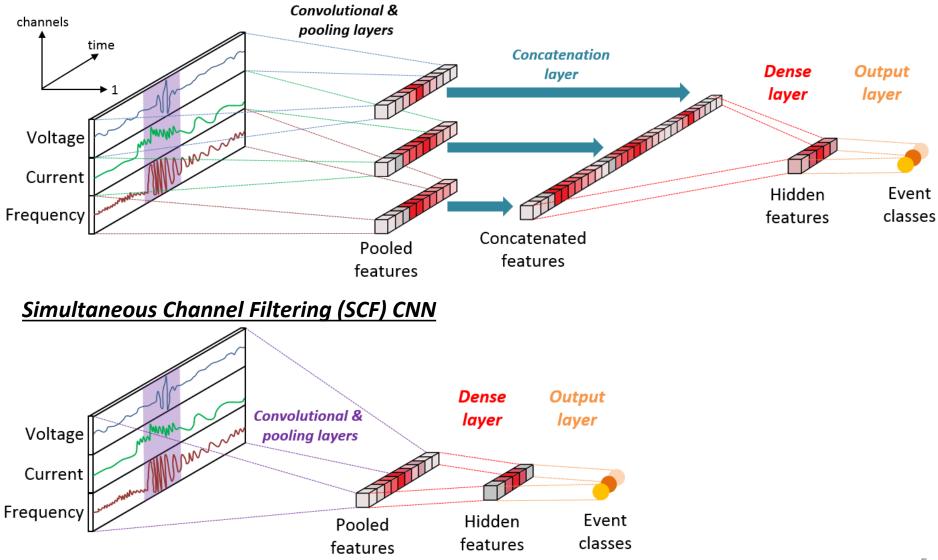


Single-Channel (SC) CNN utilizing voltage signal segments





Parallel Channel Filtering (PCF) CNN





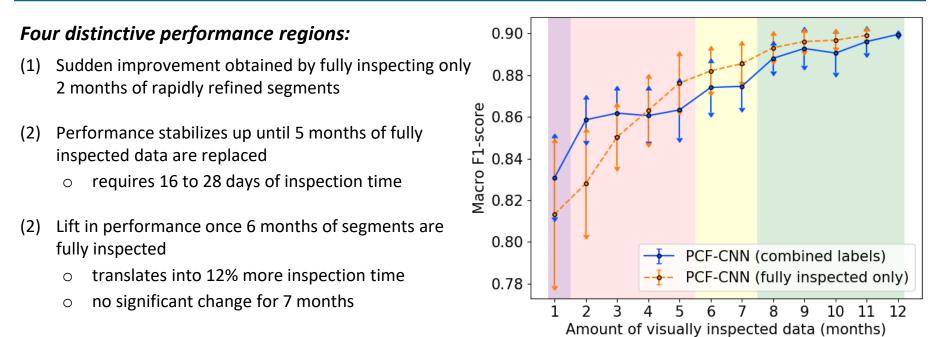
Overall Effect of Event Labeling on Event Classification

Event Logs: Rapidly refined vs partially inspected vs fully inspected 2 years at 38 PMU from Western U.S.				Event Log	Number of labeled segments		
				Event Log	Total	Grouped by type	
				D		Normal	467
Event Log	Dural the machine d	Dantin Ilu inen ested	Eullu inspected	Rapidly	1170	Line	454
Advantages	Rapidly refined	Partially inspected	Fully inspected	refined ('16)		Frequency	249
Handpicked normal	1	×	1	D (: 11	1748	Normal	1311
operation segments	•	•	•	Partially		Line	227
Narrower time intervals	 Image: A start of the start of	\checkmark	✓	inspected ('16)		Frequency	210
Single event	X	1	✓		921	Normal	481
per interval	^	<i>✓</i>		Fully		Line	229
Precise intervals (centered events)	×	1	1	inspected ('16)		Frequency	211
Visually & inspected events	×		\checkmark^+		879	Normal	426
		v		Holdout ('17)		Line	273
Labeling time *	38 hrs.	\sim 2 months (120 hrs.)	2.5 months (150 hrs.)			Frequency	180

<u>Results</u>

- **<u>CNNs</u> outperformed traditional** models in most cases
- Hierarchical models consistently outperformed the standard multiclass variants
- Multi-channel CNNs outperformed all alternatives
 - Hierarchical single channel filtering architecture was sufficient for fully refined event log
 - Hierarchical parallel channel filtering architecture was the most appropriate in the other cases
- Voltage was more relevant than current/frequency
- Increased accuracy was achieved as more curated event logs were used





- (3) Inspecting ≥ 8 months: performance is similar to the most accurate CNN (hierarchical parallel channel filtering based)
 - requires the expert to devote 2 to 2.5 months
 - ~20% to 60% more inspection time

Observations:

- When domain expert's time is **extremely limited** ⇒ label **at least 2 months** of data is suggested
- **Otherwise** ⇒ inspect ≥ 8 months to achieve significantly improved accuracy